

Lateral forces

Today we will end the discussion of Fluid Statics by discussing

Cheerios effect and its different version in which lateral forces are important.

We have discussed Buoyancy, Surface tension, and vdw forces.

① Buoyance + Surface tension

$$\sim \rho g h$$

$$\sim \gamma \frac{h}{l^2}$$

Define $l_c = \left(\frac{\gamma}{\rho g}\right)^{1/2} \rightarrow B_o = \left(\frac{l}{l_c}\right)^2 = \begin{cases} \gg 1, & G\text{-dom.} \\ \sim O(1), & \text{Today} \\ \ll 1, & C\text{-dom} \end{cases}$

size of the system

② VdW forces + Surface tension

$$\sim \frac{A}{h^3}$$

$$\sim \gamma \frac{h}{l^2}$$

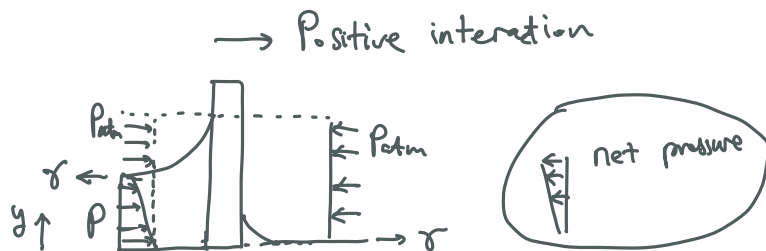
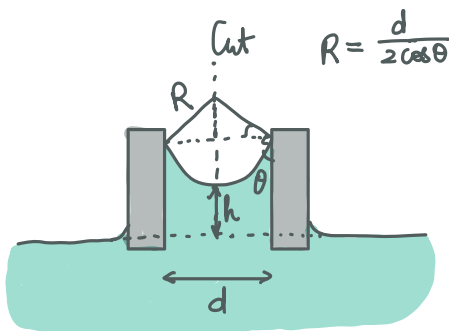
$l_{vdw} \sim \left(\frac{\gamma h c^4}{A}\right)^{1/2} \rightarrow V_\gamma = \left(\frac{l}{l_{vdw}}\right)^2 \sim O(1)$ ~~Today~~

Size of the system

[Note we have neglected gravity, requiring $h \ll \left(\frac{A}{\rho g}\right)^{1/4}$ or $l_{vdw} \ll l_c$]

Lateral capillary forces

• First, consider a simple model where d is small (what is meant by "small"?)



$P < P_{atm} \rightarrow$ Attraction between two plates

Determine h : $P_{atm} - \frac{\gamma}{R} + \rho g h = P_{atm} \rightarrow h = \frac{\gamma}{\rho g R} = \frac{2\gamma \cos \theta}{\rho g d}$

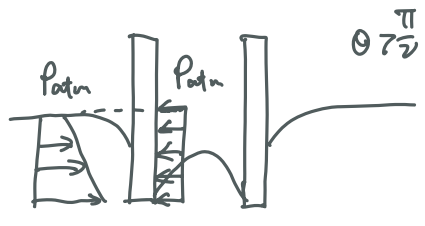
Compute plate-plate interaction:

$$\frac{F}{W} = - \int_0^h \rho g y dy = -\frac{1}{2} \rho g h^2 = -\frac{2\gamma^2 \cos^2 \theta}{\rho g d^2} = -2\gamma \left(\frac{l_c}{d}\right)^2 \cos^2 \theta$$

width of plate

Note that ① this is only true for $d \ll l_c$!

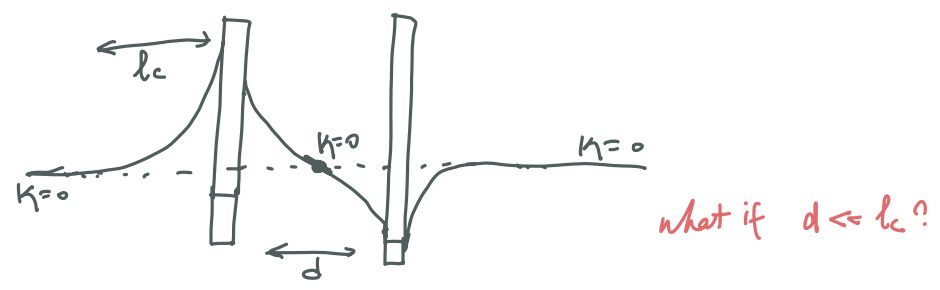
② The θ term is $\cos^2 \theta \geq 0$ (Always attractive interaction for $\theta \neq \frac{\pi}{2}$)



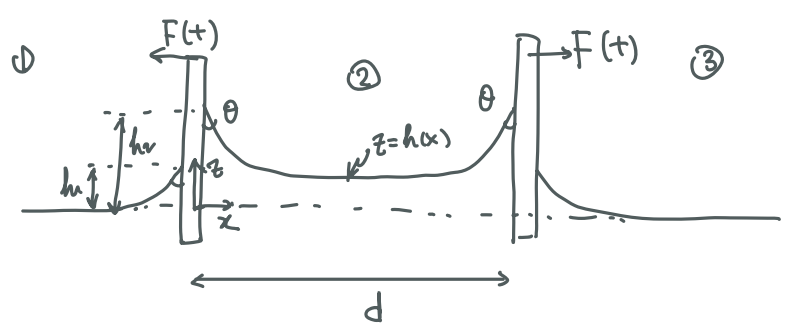
③ May guess, for plates with different surface energies

$$\frac{F}{W} = -2 \left(\frac{l_c}{d}\right)^2 \cos \theta_1 \times \cos \theta_2, \text{ ?}$$

④ Then the interaction could be repulsive, say $\theta_1 = 0, \theta_2 = \pi$



• We then consider a slightly formal analysis for far-field interactions.



$$\frac{F}{W} = -\frac{1}{2} \rho g (h_2^2 - h_1^2)$$

Line forces are cancelled!

For both ① and ②, we have $\gamma \nabla \cdot \vec{n} + \rho g h = 0$, where $\nabla \cdot \vec{n} = \frac{-h_{xx}}{(1+h_x^2)^{3/2}}$

Consider $|h_x^2| \ll 1$, we have

$$\gamma h_{xx} - \rho g h = 0$$

or

$$h_{xx} - \frac{1}{l_c^2} h = 0$$

to which the solution is $h_i(x) = A_i e^{x/l_c} + B_i e^{-x/l_c}$.

• For ①, $h(-\infty) = 0 \rightarrow B_1 = 0$
 $h_x(0) = \cot \theta \rightarrow A_1/l_c = \cot \theta$ } $\rightarrow h_1(x) = l_c \cot \theta e^{x/l_c}$

• For ② $h_x(0) = -\cot \theta$
 $h_x(d) = \cot \theta$ } $\rightarrow h_2(x) = l_c \cot \theta \frac{\cosh(\frac{d-x}{l_c}) + \cosh(\frac{x}{l_c})}{\sinh(d/l_c)}$

Therefore,

$$\frac{F}{W} = -\frac{1}{2} \rho g [h_2^2(0) - h_1^2(0)] = -\frac{\gamma}{2} \cot^2 \theta \left[\frac{(\cosh(d/l_c) + 1)^2}{\sinh^2(d/l_c)} - 1 \right] = -\frac{\gamma}{2} \cot^2 \theta / \sinh^2(d/2l_c) = -\frac{1}{2} \rho g h^2(d/2)$$

• Consider $d \ll l_c$ ($\cosh x \rightarrow 1 + \frac{1}{2}x^2$, $\sinh x \rightarrow x$)

$$\frac{F}{W} = -\frac{\gamma}{2} \cot^2 \theta \frac{4}{d^2/l_c^2} = -\frac{2\gamma^2 \cos^2 \theta}{\rho g d^2 \sin^2 \theta}$$

\uparrow d^{-2} decay (same to vol W?)

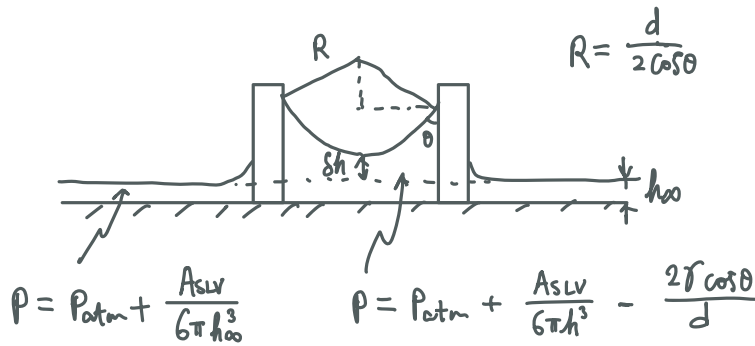
• Consider $d \gg l_c$

$$\frac{F}{W} = -\frac{\gamma}{2} \frac{\cot^2 \theta}{\sinh^2(d/2l_c)} \approx -\frac{2\gamma \cot^2 \theta}{e^{d/l_c}}$$

\uparrow Exponential decay.

• Lateral immersion forces

Now neglect buoyancy / gravitational forces and consider a limiting case "small d"



$$\rightarrow \frac{A_{sL} V}{6 \pi} \left(\frac{1}{h^3} - \frac{1}{h_{\infty}^3} \right) = \frac{2 \gamma \cos \theta}{d}$$

Let $h = h_{\infty} + \delta h$ where $\delta h \ll h_{\infty}$ so that $\frac{1}{h^3} = \frac{1}{h_{\infty}^3 (1 + \frac{\delta h}{h_{\infty}})^3} \stackrel{\text{Linearization}}{=} \frac{1}{h_{\infty}^3} \left(1 - 3 \frac{\delta h}{h_{\infty}} \right)$

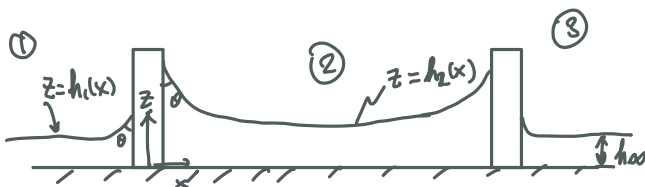
$$\rightarrow \frac{A_{sL} V}{6 \pi} \left(- \frac{3 \delta h}{h_{\infty}^4} \right) = \frac{2 \gamma \cos \theta}{d}, \text{ i.e., } \delta h = \frac{4 \pi \gamma \cos \theta}{(-A_{sL} V) d} h_{\infty}^4$$

In this case, the interaction takes the form

$$\frac{F}{W} = \delta h \left(\frac{A_{sL} V}{6 \pi h_{\infty}^3} \right) = - \frac{2}{3} \frac{\gamma h_{\infty} \cos \theta}{d} \quad (\text{Always attractive!})$$

↑
Unlike gravity, p is a constant here.

But what is meant by "small d"? - There should be a length-scale l_{vdw} like l_c



For both ① and ②, we have

$$P_{atm} + \gamma \cdot \frac{1}{h} + \frac{A_{SLV}}{6\pi h^3} = P_{atm} + \frac{A_{SLV}}{6\pi h_0^3}$$

or

$$h_{xx} - \frac{A_{SLV}}{6\pi\gamma} \frac{1}{h^3} = -\frac{A_{SLV}}{6\pi\gamma h_0^3}$$

Consider $h \sim h_0$, a natural lateral length is

$$l_{vdw} = \left(\frac{2\pi\gamma h_0^4}{|A_{SLV}|} \right)^{1/2} \sim 100 \mu m$$

$\gamma \sim 0.1 \text{ N/m}$
 $A \sim 10^{-20} \text{ J}$
 $h_0 \sim 100 \text{ nm} ? \text{ Why}$

Also note that gravity is neglected, implying

$$l_{vdw} \ll l_c \rightarrow \frac{6\pi\gamma h_0^4}{|A_{SLV}|} \ll \frac{\gamma}{\rho g} \rightarrow h_0 \ll \left(\frac{A_{SLV}}{6\pi\rho g} \right)^{1/4} \sim \left(\frac{10^{-20} \text{ J}}{6\pi \times 10^4 \frac{\text{N}}{\text{m}^3}} \right)^{1/4} \approx 500 \text{ nm}$$

This may appear more natural in a linearized version $h = h_0 + \delta h$

$$\delta h_{xx} - \frac{A_{SLV}}{6\pi\gamma h_0^3} (1 - 3\delta h) = \frac{A_{SLV}}{6\pi\gamma h_0^3}$$

$$\Rightarrow \delta h_{xx} - \underbrace{\frac{A_{SLV}}{2\pi\gamma h_0^3}}_{1/l_{vdw}^2} \delta h = 0$$

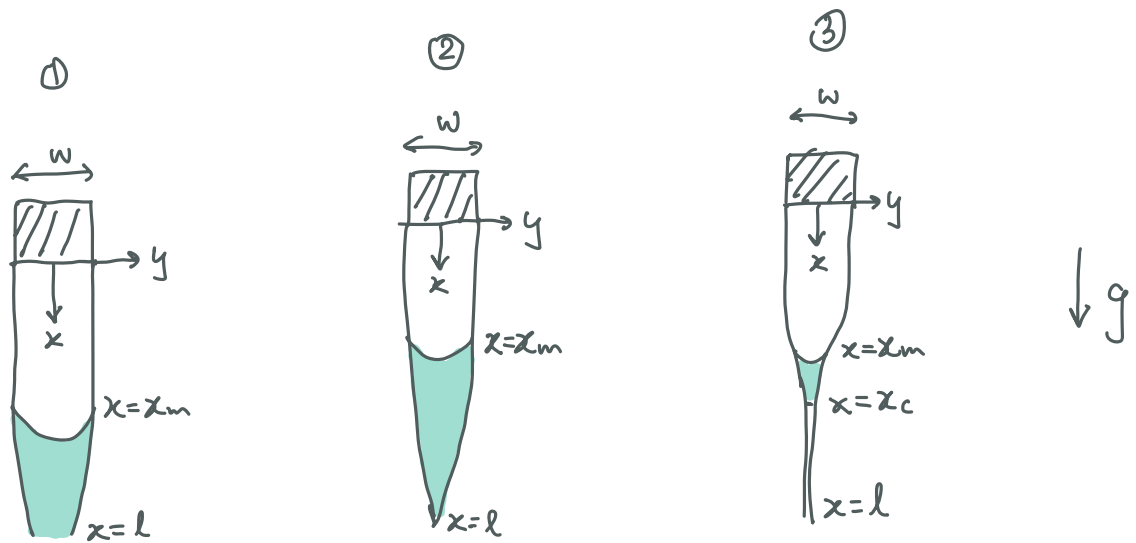
It may be a course project to study linearized and fully nonlineary version

of lateral immersion forces for $\theta_1 \neq \theta_2$.

Elastocapillarity

Elastocapillary rise

Slender structures are often very bendable. The question is how the elastic and surface energies interplay. We then consider the following problem (Kim & Mahadevan JFM 2006) - Capillary rise between elastic sheets



More relevant examples: wetted paintbrush/hairs, closure of airways within the lung, and stiction of MEMS.

Aside: As $t \ll l$ (geometrically slender) and $w \ll l$ (geometrically linear),

it is possible to use $\epsilon = t/l$ as the small parameter, reducing Navier

Cauchy equations to linear plate equation / Euler-Bernoulli beam equation:

$$\nabla^4 y(x) = p(x)$$

• Case 1

No pressure in the "dry" part: $y'''' = 0$, $0 < x < x_m$

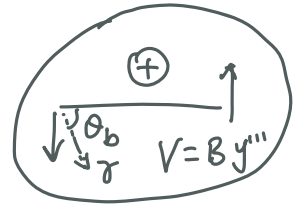
In the "wet" part, $B y'''' = -\cancel{\gamma} \cancel{\kappa_b} - \rho g(l-x)$ 0 in experiments

Bending stiffness

Curvature of the meniscus at the bottom ($x=l$)

Need 9 boundary conditions / matching conditions to solve the 2 fourth-order ODE + the unknown x_m .

• At $x=0$, $y(0) = \frac{1}{2}W$, $y'(0) = 0$

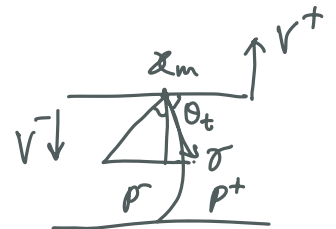


• At $x=l$, $y''(l) = 0$, $B y''''(l) = \gamma \sin \theta_b \approx \gamma$

• At $x=x_m$, $[y(x_m)] = [y'(x_m)] = [y''(x_m)] = 0$

$$[f(x_m)] = f(x_m^+) - f(x_m^-)$$

$$B [y''''(x_m)] = \gamma \sin \theta_t$$



$$\rho^+ - \rho^- = -\rho g(l-x_m) = -\gamma \cos \theta_t / y(x_m)$$

Use l to scale the coordinate and w to scale the sheet deflection

$$X = x/l, \quad Y = y/w, \quad l_c = \left(\frac{\gamma}{\rho g}\right)^{1/2}, \quad l_{ec} = \left(\frac{B}{\gamma}\right)^{1/2}$$

$$\Rightarrow Y'''' = \begin{cases} 0, & 0 < X < X_m \\ \frac{l^5}{l_c^2 l_{ec}^2 w} (X-1), & X_m < X < 1 \end{cases}$$

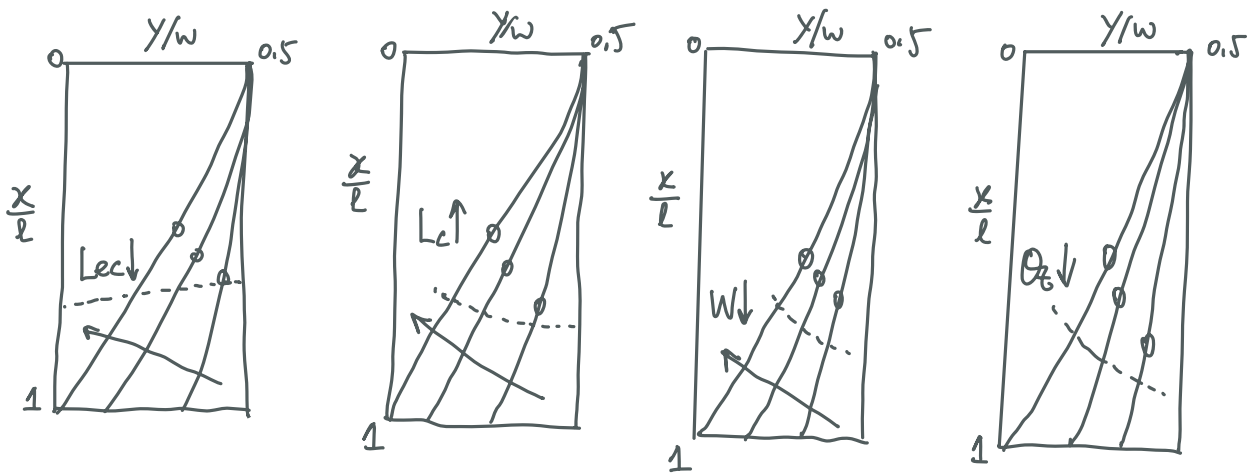
subject to

$$Y(0) = \frac{1}{2}, \quad Y'(0) = 0, \quad Y''(1) = 0, \quad Y'''(1) = \frac{l^3}{w l_c^2}$$

$$[Y(x_m)] = [Y'(x_m)] = [Y''(x_m)] = 0$$

$$[Y'''(x_m)] = \frac{l^3}{w l_c^2} \sin \theta_t, \quad Y(x_m) = \frac{l_c^2}{l w} \cos \theta_b (1 - x_m)^{-1}$$

Key parameters: L_{ec} , L_c , $W = w/l$ and θ_t



..... Capillary rise between rigid sheets.

• Case ②

The same except for $B y'''(l) = \tau \rightarrow Y(l) = 0$

• Case ③

$$p(x) = \begin{cases} 0, & 0 < x < x_m \\ \rho g(x - x_c), & x_m < x < x_c \end{cases}$$

BCs and matching conditions are the same at $x=0$ & $x=x_m$ (7 conditions)

$$y(x_c) = y'(x_c) = 0$$

$$y''(x_c) = 0 \rightarrow \text{To solve } x_c$$

• Vertical force balance




$$\int_{x_m}^{x_c} \rho g y dx = \gamma \cos \theta_t - \int_{x_m}^{x_c} B y'''' y' dx$$

$$\int_{x_m}^{x_c} B y'''' y' dx = \int_{x_m}^{x_c} \rho g (x - x_c) y' dx$$

$$= \rho g (x - x_c) y \Big|_{x_m}^{x_c} - \int_{x_m}^{x_c} \rho g y dx$$

$$= -\rho g (x_m - x_c) y(x_m) - \int_{x_m}^{x_c} \rho g y dx$$

$$\Rightarrow \rho g (x_m - x_c) = \frac{-\gamma \cos \theta_t}{y(x_m)} \quad (\checkmark \text{ self-constant})$$

•  $2 \times \frac{1}{2} B \gamma''^2(x_c) = 2\gamma_{sl} - \gamma_{ss} = -S = \Gamma - 2\gamma \cos \theta_t$
 $\Gamma = 2\gamma_{sv} - \gamma_{ss}$
 \uparrow Interface spreading parameter

$S > 0$, $\gamma_{ss} > 2\gamma_{sl}$, \rightarrow There will be a thin layer of liquid.

(Occurs for small Γ , large γ , small $\theta_t \rightarrow \gamma''(x_c) = 0$)

$S < 0$, $\gamma_{ss} < 2\gamma_{sl} \rightarrow$ There will be a jump in curvature

(Occurs for large Γ , small γ , large $\theta_t \rightarrow \gamma''(x_c) = (-S/B)^{1/2}$).

• If $S > 0$, $\gamma''(x_c) = 0$. As $x_0 = x_c - x_m \rightarrow 0$, whether the problem

will decay to $\gamma'''' = 0$, $0 < x < x_c$, subject to



$$\gamma(0) = \frac{1}{2} w, \quad \gamma'(0) = 0, \quad \gamma(x_c) = 0, \quad \gamma'(x_c) = 0, \quad \gamma'' = \left[\frac{2(\gamma_{sv} - \gamma_{sl})}{B} \right]^{1/2}$$

$$?? = \left(\frac{2\gamma \cos \theta_t}{B} \right)^{1/2}$$