The Dugdale - Barenblatt model

In a linuar elastic materiol, K is related to the coefficient on the singular '/ a Fress terms, arising near a craek Hp. However, we have noted that real materials cannot support inifinite strenses. Why can K still be used as a frouture criterion if it doesn't represent the reality?

 (65)

Consider the following model for nonlinear behavior near the crack tip. We will only analyze the nonlinear behavior on the plane ahead of the crack tip and will assume that δ yy is limited to a peak value of δ . Later, we will show Syy can take any form under 8SY conditions.

2M can be used to represent ^a vast number of fracture mechanisms including plastic tearing, atomic de-cohesion, fiber pull-out in composite fracture.

There are also a number of CZMs, but let's focus on constant so at this moment!

The crack model looks like

We can set our origin at the real crack tip or the mode crack tip Let us choose the latter since we've already have the solution in HW3:

At the mode craek tip, we have

 $K_{tip} = K_{app} + K_{czm}$
 $K_{tip} = K_{app} + K_{czm}$

$$
= k_{1} + \int_{0}^{k} -\frac{3}{2} d \frac{g}{r} \sqrt{\frac{2}{\pi g}}
$$

What is Ktip? If Ktip#0, then Syy ahead of the model crock tip will go to ∞ . This is prohibited by the CZM (it arrods singularity by tuning R).

$$
\Rightarrow K_{\mathcal{I}} - \oint_{\circ} \frac{1}{\pi} \int_{0}^{R} g^{-1/2} dg = K_{\mathcal{I}} - \frac{2}{\pi} \oint_{0} 2 g^{\frac{1}{2}} \Big|_{0}^{R} = 0
$$

$$
\Rightarrow K_{\mathcal{I}} = \frac{\sqrt{2}}{\sqrt{\pi}} \oint_{0} R^{\frac{1}{2}} \quad \text{or} \quad R = \frac{\pi}{8} \left(\frac{K_{\mathcal{I}}}{\oint_{0}^{2}} \right)^{2} \quad \text{size of} \quad \text{Digdale} \quad \text{plus} \quad \text{time} \quad \text{time}
$$

Before we say fracture ocears when $k_{\text{I}} = k_{\text{Ic}}$ or $\frac{k_{\text{I}}^k}{E^1} = \int_{S}$. Now, we need a new criterion. This criterion is obvious from the point of view of physics

$$
\delta(z=-R) = \delta_c
$$

To compute the crack opening displacement, we need to calculate \vec{z}_1 & $\hat{z}_1 = \int \vec{z}_1 d_2$, since 2μ $U_y = \frac{1}{2} (K_{y+1})$ $\mathbb{I}_m \hat{Z}_1 - y$ $\mathbb{R} \hat{Z}_1$.

$$
Z_{\text{I}} = \frac{K_{\text{I}}}{\sqrt{2\pi z}} - \int_{0}^{R} \frac{\delta_{\text{I}}\sqrt{g}}{\pi \sqrt{g}(z - \zeta)} d\zeta
$$

$$
= \frac{K_{\text{I}}}{\sqrt{2\pi z}} - \frac{\delta_{\text{I}}}{\pi \sqrt{g}} \left[2\sqrt{R} - 2\sqrt{z} \arctan \sqrt{\frac{R}{z}} \right]
$$

$$
= \frac{K_{\text{I}}}{\sqrt{2\pi z}} - \frac{2\zeta_{\text{I}}}{\pi \sqrt{g}} \frac{\sqrt{g}}{\sqrt{g}} - 2\sqrt{z} \arctan \sqrt{\frac{R}{z}}
$$

$$
\frac{2\zeta_{\text{I}}}{\pi} \arctan \sqrt{\frac{R}{z}}
$$

$$
= \frac{2\zeta_{\text{I}}}{\pi} \left(\sqrt{R_{\text{I}}} + z \arctan \sqrt{\frac{R}{z}} - R \arctan \sqrt{\frac{R}{R}} \right)
$$

Need a bit thougt to compute arctan x $Sin\theta = \frac{1}{2i}(e^{i\theta} - e^{-i\theta}) = -i \sinh i\theta$
 $cos\theta = \frac{1}{2}(e^{i\theta} + e^{-i\theta}) = cosh i\theta$
 $tan\theta = -i \tanh i\theta$
 $x = tan \theta = -i \tanh i\theta$
 $x = tan \theta = -i \tanh i\theta$
 $x = tan \theta = -i \tanh i\theta$

On the crack surfaces, $Z = re^{\pm i\pi}$, $y = o^{\pm}$:

$$
\hat{\zeta}_{1} = \frac{2\phi}{\pi} \left[\sqrt{R_{\Gamma}} e^{\pm i \frac{\pi}{2}} + r e^{\pm i \pi} \frac{1}{2i} \ln \left(\frac{1 + i \sqrt{R_{\Gamma}} e^{\mp i \frac{\pi}{2}}}{1 - i \sqrt{R_{\Gamma}} e^{\mp i \frac{\pi}{2}}} \right) - R \frac{1}{2i} \ln \left(\frac{1 + i \sqrt{R_{\Gamma}} e^{\pm i \frac{\pi}{2}}}{1 - i \sqrt{R_{\Gamma}} e^{\pm i \frac{\pi}{2}}} \right) \right]
$$
\n
$$
= \frac{2\phi}{\pi} \left[\pm i \sqrt{R_{\Gamma}} + i \frac{\Gamma}{2} \ln \left(\frac{1 \pm \sqrt{R_{\Gamma}}}{1 \mp \sqrt{R_{\Gamma}}} \right) + i \frac{R}{2} \ln \left(\frac{1 \mp \sqrt{r_{\Gamma}}}{1 \pm \sqrt{r_{\Gamma}} R} \right) \right]
$$

Note that
$$
Re \left[ln \left(\frac{1+x}{1-x} \right) \right] = Re \left[ln \left(\frac{1+x}{1-x} \right) e^{in\pi} \right] = ln \left| \frac{1+x}{1-x} \right|
$$
, $Re \left[ln \left(\frac{1-x}{1+x} \right) \right] = - ln \left| \frac{1+x}{1-x} \right|$
\n
$$
\text{Im} \left[\hat{Z}_{I} \right] = \frac{24}{\pi} \left(\pm \sqrt{RT} \pm \frac{\Gamma}{2} ln \left| \frac{1+\sqrt{RT}}{1-\sqrt{RT}} \right| + \frac{R}{2} ln \left| \frac{1+\sqrt{TR}}{1-\sqrt{TR}} \right| \right)
$$
\n
$$
= \frac{1+ \sqrt{TR}}{1-\sqrt{TR}} \right]
$$
\n
$$
= \frac{24}{\pi} \left(\pm \sqrt{RT} \pm \frac{r-R}{2} ln \left| \frac{1+\sqrt{TR}}{1-\sqrt{TR}} \right| \right)
$$
\n
$$
\Rightarrow U_{J}(r, \theta = \pm \pi) = \frac{K+1}{\pm \mu} \cdot \frac{24}{\pi} \cdot \left(\pm \sqrt{RT} \pm \frac{r-R}{2} ln \left| \frac{1+\sqrt{TR}}{1-\sqrt{TR}} \right| \right)
$$

$$
\frac{u_{q}}{R}\left(r, \theta = \pm \pi\right) = \pm \frac{46}{\pi E} \left[\sqrt{\frac{r}{R} - \frac{1}{2}\left(1 - \frac{r}{R}\right)} \ln\left|\frac{1 + \sqrt{r/R}}{1 - \sqrt{r/R}}\right|\right]
$$
\n
$$
= \begin{cases}\n\frac{2}{3}\left(\frac{r}{R}\right)^{3/2} & \text{as } \frac{r}{R} \to 0 \\
1 & \text{as } \frac{r}{R} \to 1\n\end{cases}
$$

$$
\oint_{\mathcal{E}} \int_{\mathfrak{f}_{\mathfrak{t}}} \int_{\mathfrak{X}}^{y} \times \text{COD}(\mathfrak{r}=\mathsf{R}) = u_{y}(\mathsf{R},\mathfrak{n}) - u_{y}(\mathsf{R},-\mathfrak{n}) = \frac{\delta \delta_{\mathfrak{e}}}{\pi \epsilon} \mathsf{R}
$$

Propagation \Rightarrow $\frac{\partial \mathcal{S}_{0}}{\partial \mathbf{F}}R=\mathcal{S}_{0}$ $\frac{\sqrt{6}}{\pi \Gamma} \cdot \frac{\pi}{8} \left(\frac{K_{\pi}}{6} \right)^2 = \delta_c$ $\frac{K_{\tau}^{2}}{F} = 6.5_{c} \Leftrightarrow \int f = 6_{c}$

So even though we have no singularity a lead of the crack tip, we still get crack propagation when $g = g_c$ or equivalently when $K_{\mathcal{I}} = K_{\mathcal{I}c} = \sqrt{g_c E} = \sqrt{s_c \varepsilon E}$. In the semi-infinite crock problem, we have SSY coaditions immediately. Let's move on to the center crack problem in which we have a length scale - initial crack length.

You may use HW3 (problem 1) to show that

Crack propagation > COD($x = \pm a$) = δ_c Will show this is J under SSY $\delta_0 \delta_0 = \frac{\delta}{\pi} \frac{\delta_0^2 a}{E} \ln \left[\sec \left(\frac{\pi}{2} \frac{\delta}{\delta_0} \right) \right] = \frac{\pi a \delta^2}{E'} \left[1 + \frac{\pi^2}{24} \left(\frac{\delta}{\delta_0} \right)^2 + \cdots \right]$ $=\frac{\pi^2}{8} \left(\frac{6}{8}\right)^2 + \frac{\pi^4}{192} \left(\frac{6}{8}\right)^4 + \cdots$ Will show this is J under LSY .

 SSY : in the limit as $R \ll a$ (i.e., $d \ll d_0$)</u> $K_{\tau} = \sqrt{\pi(\alpha + \beta)} \rightarrow \sqrt{\pi \alpha}$, $\int_{0}^{ss\gamma} = \frac{K_{\tau}^{2}}{F} = \frac{\pi \alpha \sqrt{2}}{F}$, $\sqrt{2}^{ss\gamma} = \left(\frac{F^{\prime}\zeta_{c}}{F^{\prime}}\right)^{\frac{1}{2}}$

LSY: R/a is not too small, the apparent strength is $\begin{aligned}\n\zeta_c &= \frac{2\phi}{\pi} \sec^{-1} \left[\exp \left(\frac{\pi E^{\prime} \zeta_c}{8 \zeta_o^2 a} \right) \right] = \frac{2 \zeta_o}{\pi} \sec^{-1} \left[\exp \left(\frac{\pi^2 \zeta_c^{s_1}}{8 \zeta_o^2} \right) \right] \\
&= \left\{ \zeta_c^{ST} \left[1 - \frac{\pi^2}{48} \left(\frac{\zeta_c^{ST}}{50} \right)^2 + \cdots \right] , \text{ for Large a} \right\}\n\end{aligned}$ $=\begin{cases} \sqrt[3]{5} \left[1-\frac{\pi^2}{48}\left(\frac{\sqrt{5}}{40}\right)^2+\cdots\right] , & \text{for large } a \\ \pi^2, & \text{for small } a \end{cases}$

The J integral

We will show that J is a path-independent integral and is equal to the energy release rate in nonlinear elastic materials

First define the strain energy density in ^a nonlinear material as

$$
W = \int_{0}^{\xi} \delta_{ij} d\zeta_{ij} \longrightarrow \delta_{ij} = \frac{\partial W}{\partial \xi_{ij}}, \text{ i.e., } W = \int_{0}^{\xi} \frac{\partial W}{\partial \xi_{j}} d\zeta_{ij} = \int_{0}^{\xi} dW
$$

So our governing equations for ^a small deformation problem in this nonlinear material are

 $(*$ We could generalize to large deformation, but we'll not concern ourselves with $this$ complication $*)$

$$
\pi = \int_{A} W dA - \int_{R} t_i u_i dP
$$

\n
$$
\int_{S} = -\frac{DT}{Da}, \text{ where } \frac{D}{Da} = \frac{\partial}{\partial a} \Big|_{x_i, x_2} + \frac{\partial}{\partial x_i} \Big|_{a} \frac{\partial x_i}{\partial a} = \frac{\partial}{\partial a} \Big|_{x_i, x_1} - \frac{\partial}{\partial x_i} \Big|_{a} + x_i \to x + dx_i
$$

\n
$$
\int_{S} = -\frac{DT}{Da}, \text{ where } \frac{D}{Da} = \frac{\partial}{\partial a} \Big|_{x_i, x_2} + \frac{\partial}{\partial x_i} \Big|_{a} \frac{\partial x_i}{\partial a} = \frac{\partial}{\partial a} \Big|_{x_i, x_1} - \frac{\partial}{\partial x_i} \Big|_{a} + x_i \to x + da
$$

 $\textcircled{7}$

Pistare for da (Tremains the same)

Picture for dx_1 (different 7 but same a)

$$
\hat{G} = -\frac{p}{\partial a} \int_{A} W dA + \frac{p}{\partial a} \int_{\vec{R}} t \hat{i} u_{\hat{i}} dP
$$
\n
$$
= \frac{\partial}{\partial x_{\hat{i}}} \int_{A} W dA - \frac{\partial}{\partial a} \int_{A} W dA + \int_{P} t \hat{i} \left(\frac{\partial u_{\hat{i}}}{\partial a} - \frac{\partial u_{\hat{i}}}{\partial x_{\hat{i}}}\right) dP
$$
\nSince $\begin{array}{ccc}\n\frac{\partial t_{\hat{i}}}{\partial a} & \frac{\partial t_{\hat{i}}}{\partial a} & \frac{\partial t_{\hat{i}}}{\partial a} \\
\frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} \\
\frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} \\
\frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} \\
\frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} \\
\frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} \\
\frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} \\
\frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} \\
\frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} \\
\frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{\partial a} & \frac{\partial u_{\hat{i}}}{$

Note that $\frac{\partial}{\partial x_1}$ cannot be taken inside the first integral because the area A (x,, x,) has has changed to A(x1+dx1, x2) as the contour moves. However, $\frac{3}{50}$ can be taken inside the second integral, i.e., $\frac{\partial}{\partial \alpha} \int_{A} W dA = \int_{A} \frac{\partial W}{\partial \alpha} dA$.

for crack tip solutions, even in nonlineur elastic materials, we want finite energy in any finite area around the craek tip.

$$
W dA = W r dr d\theta
$$
 $fint e \rightarrow W - \frac{1}{r}$, $r = (x_1^2 + x_2^2)^{1/2}$

This also means that $\frac{\partial W}{\partial \alpha} \backsim \frac{1}{\Gamma}$ and $\frac{\partial W}{\partial \alpha} dA$ is NOT singular. So, we can apply divergence theorem to this term.

$$
\int_{A} \frac{\partial w}{\partial \alpha} dA = \int_{A} \frac{\partial w}{\partial \ell j} \frac{\partial \ell j}{\partial \alpha} dA = \int_{A} \delta_{ij} \frac{\partial u_{ij}}{\partial \alpha} dA = \int_{A} \left[\langle \delta_{ij} \frac{\partial u_{i}}{\partial \alpha} \rangle_{ij} - \langle \delta_{ij} \frac{\partial u_{i}}{\partial \alpha} \rangle_{ij} \right] dA = \int_{P} \delta_{ij} \frac{\partial u}{\partial \alpha} u_{j} dP
$$

$$
\Rightarrow G = \frac{\partial}{\partial x_1} \int_A W dA - \int_{\mathcal{A}} \frac{\partial u_i}{\partial a} dP + \int_{\mathcal{P}} \frac{\partial u_i}{\partial a} dP - \int_{\mathcal{P}} t_i \frac{\partial u_i}{\partial a} dP - \int_{\mathcal{P}} t_i \frac{\partial u_i}{\partial x_1} dP
$$

 \bigcirc

Now, consider $\frac{\partial}{\partial x_1} \int_A w dA$

 dx_1 is uniform over the entire contour. $\rightarrow \Delta W = \int W dx_1 dx_2 = dx_1 \int W dx_2$

$$
\Rightarrow \Delta W = dx_1 \int_{T} W r_1 dT \Rightarrow \frac{\partial}{\partial x_1} \int_{A} W dA = \lim_{\begin{subarray}{l} d \times b \\ d \times d \end{subarray}} \frac{\int_{A(x_1 + dx_1)} W dA - \int_{A(x_1)} W dA}{dx_1}
$$

$$
= \lim_{\begin{subarray}{l} d \times b \\ d \times d \end{subarray}} \frac{\Delta W}{dx_1} = \int_{T} W r_1 dT
$$

Finally, we have

$$
G = \int_{\vec{l}} W n_{i} - t_{i} \frac{\partial U_{i}}{\partial x_{i}} dT = J \qquad (J.R. R_{ice} JAM. 1968)
$$

Sty n_{j} u_{i,1}

Now show J is path independent Consider ^J around any contour not surrounding a singularity

 \bigcirc

$$
\int_{\Gamma} \mathbf{w} \cdot d\mathbf{y} = \int_{\Gamma} \mathbf{w} \cdot \mathbf{n}_1 - d\mathbf{y} \cdot d\mathbf{y}
$$

$$
\int_{\Gamma} \mathbf{w} \cdot \mathbf{n}_1 d\mathbf{y} = \int_{A} \mathbf{w}_{11} dA = \int_{A} \frac{\partial \mathbf{w}}{\partial \mathbf{\epsilon}_{ij}} u_{ij1} dA = \int_{A} (\delta_{ij} u_{ij1})_{ij} dA
$$

$$
= \int_{\Gamma} d_{ij} u_{ij1} \cdot \mathbf{n}_j dA \rightarrow \mathbf{J} = 0
$$

Back to our cracked body

$$
T_2
$$

\n T_3
\n T_4
\n T_5
\n T_6
\n T_7
\n T_8
\n T_9
\n T_1
\n T_2
\n T_1
\n T_2
\n T_3
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\n T_9

Note that on $\frac{1}{2}$, $\frac{1}{4}$, $n_1 = 0$, $t_1 = 0$ \Rightarrow $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ $\frac{1}{2}$ \frac

$$
\Rightarrow \oint = \mathbb{J}_{\vec{l}} = -\mathbb{J}_{\vec{l}_{3}}
$$
\nAny arbitrary contour surrounding the crack tip counterclockuisely (for crack growing 1. the right)
\n
$$
\Rightarrow \oint = \mathbb{J} \& \mathbb{J} \text{ is path-independent}
$$

Examples from $HW1$: $J = \int_{R} W r_1 - S_{ij} r_j u_{i1} dV$

no.ae 7,4 ni ^o 4 ⁰ fromthe natural axis ofthe arm upward positive 7 ^R ¹ Exx KY GEEKY all otherEij Gj ⁰

$$
W = \frac{1}{2} \mathcal{E}_{x_{x}} \mathcal{E}_{y_{x}} = \frac{1}{2} E K^{2} y^{2} \qquad dF = d(-y)
$$

$$
J_{1} = \int_{\frac{1}{2}}^{\frac{1}{2}} \frac{1}{2} E K^{2} y^{2} \cdot (-1) - EY y \cdot (-1) \cdot Ky \cdot d(y)
$$

$$
= \int_{\frac{1}{2}}^{\frac{1}{2}} \frac{1}{2} E K^{2} y^{2} dy = \frac{1}{2} E I_{\frac{2}{2}} K^{2} = \frac{1}{2} B K^{2} = \frac{K^{2}}{2 E I_{z}} b
$$

$$
\begin{aligned}\n\overline{J}_5: \quad n_1 = -1, \quad \xi_{xx} = K_y \quad \text{(taking y from the neutral axis of the arm)} \\
\rightarrow \overline{J}_5 = \frac{1}{2} B K^2 = \frac{M^2}{2 E I_z b} \\
\overline{J} = \overline{J}_1 + \overline{J}_2 + \overline{J}_3 + \overline{J}_4 + \overline{J}_5 = B K^2 = \frac{M^2}{E I_z b}\n\end{aligned}
$$

 $G = G_c \rightarrow K = \left(\frac{G_c}{R}\right)^{1/2}$ A jump in curvature since T_1 , T_5 could be taken to close to the crack tup.

 \bigcirc

4	The x direction must be chosen in the direction of a direction of the equation of the equation.																																											
b) $\frac{61}{2}$	$\frac{15}{2}$	$\frac{15}{4}$ </td																																										

The x-direction must be chosen
\n
$$
\frac{4}{2}
$$
\n
$$
\
$$

$$
\begin{bmatrix} . & n_1 = 0 , n_2 = -1 , & \text{for } s \text{ (symmetry)} , & d \end{bmatrix} = dx_1
$$

$$
\int_{2} = \int_{0}^{k} 0 - 6i2} \cdot (-1) \, \text{M}_{2}^{10} \, dx_{1} = 0
$$

 $\overline{1}_3$: $n_1=1$, $n_2=0$, $\measuredangle_{i\overline{j}}=0$ \rightarrow $\overline{1}_3=0$

$$
T_4
$$
: $n_1 = 0$, $t_1 = 0$ \rightarrow $T_4 = 0$
\n T_5 : $n_1 = -1$, $n_2 = 0$, $\measuredangle_{11} = -\frac{p}{bt}$, $\measuredangle_{11} = -\frac{p}{t_2^2 bt}$, $dT = -\frac{1}{t_2^2 bt}$
\n
$$
T_5 = \int_{b}^{b} \left[\frac{p^2}{2E_b^2 b^2} \cdot (-1) - \frac{p}{bt} \left(-\frac{p}{E_a^2 bt} \right) \right] d(-x_2) = \frac{p^2}{2E_b^2 bt^2}
$$
\n
$$
\Rightarrow \boxed{J = J_1 + J_3 = \frac{p^2}{bt^2} \left(\frac{1 - y_1^2}{E_1} + \frac{1 - y_2^2}{2E_2} \right)}
$$

仍

For a more general cohesive zone model, we have

$$
\int = \int_{-R}^{0} \zeta_{22} u_{231}^{-} dx_1 + \int_{0}^{R} \zeta_{22} u_{231}^{+} dx_1
$$

\n
$$
= \int_{0}^{-R} \zeta_{22} (u_{231}^{+} - u_{231}^{-}) dx_1
$$

\n
$$
= \int_{0}^{-R} \zeta_{22} (u_{231}^{+} - u_{231}^{-}) dx_1
$$

\n
$$
= \int_{0}^{-R} \zeta_{23} (u_{231}^{+} - u_{231}^{-}) dx_1
$$

\n
$$
= \int_{0}^{\delta(x_{1}-\delta)} \zeta_{23} (u_{311}^{+} - u_{311}^{-}) dx_1
$$

- \bigcirc • Under SSY conditions and Mode I, $\overline{J} = \frac{G}{g} = \frac{K_I^2}{E'}$. It does not depend on what cohesive zone law looks like
- . Under LSY conditions, we can still take a J contour to closely surround the fracture process zone and obtain

$$
\mathcal{L} = \int_{0}^{\delta_{\mathbf{t}}} \phi(\delta) d\delta
$$

where δ_t is the opening at the back edge of the process zone (this expression for J is valid prior to propagation). Propagation occurs when $\underline{\delta_t} = \delta_c$, corresponding to

$$
\int = \int_0^{\delta_c} \langle \zeta(\delta) \, d\delta = \int_c
$$

Hence, this model predicts propagation when J reaches S_c . This is equivalent to a fracture criterion based on a critical crack opening displacement. Also note that under LSY conditions, $\overline{J} \neq \frac{K_{\overline{x}}^2}{E^1}$. For Dugdate model in the center cracked panel

$$
\mathcal{J} = \frac{\mathcal{K}_{\underline{x}}}{E^{12}} \left[\mathcal{I} + \frac{\pi^2}{24} \left(\frac{\mathcal{S}}{\mathcal{S}_0} \right)^2 + \cdots \right] > \mathcal{J}_{ss}
$$

Therefore. J is powerful tool when dealing with nonlinearities and LSY.

The HRR fields

 H utchinson JMPS v.16 pp. 13-31 (1968); Rice & Rosengren JMPS v16. pp. 1-12 (1968)

$$
\frac{\delta}{\lambda} \qquad \text{polymers (n>1)}
$$
\n
$$
\frac{\epsilon}{\epsilon_{\gamma}} = \frac{\delta}{\epsilon_{\gamma}} + \alpha \left(\frac{\delta}{\epsilon_{\gamma}}\right)^{n}
$$
\n
$$
n \rightarrow 1 \rightarrow \text{Linear law}
$$
\n
$$
\frac{\delta_{ij}}{\delta_{\gamma}} = \left(\frac{J}{\alpha \epsilon_{\gamma} \delta_{\gamma} I_{n}} + \frac{1}{\Gamma}\right)^{\frac{1}{n+1}} \sum_{\delta_{ij}(\theta)}^{n}
$$
\n
$$
\text{Universal angular functions}
$$
\n
$$
u_{i} = \alpha \epsilon_{\gamma} \cdot \left(\frac{J}{\alpha \epsilon_{\gamma} \delta_{\gamma} I_{n}} + \frac{1}{\Gamma}\right)^{\frac{n}{n+1}} \sum_{i}^{n} (0)
$$

Domain integral method for J calculations (neeful in FEM)

$$
\overline{J} = \int_{\overline{\Gamma}} \left(W n_1 - \measuredangle_{\hat{j} i} n_j u_{i,1} \right) d\overline{\Gamma}
$$

 \widehat{F}

Define a sufficiently smooth $q(x_1, x_2)$ such that $q=1$ on \int and $q=0$ on \int_{2}^{π} . Since $\overline{\theta_{\vec{l}i}} = \overline{\theta_{\vec{l}i}} = o$ ($n_i = o$, $t_i = o$ on crack faces), we have

$$
J = \int_{\Gamma^{+}\Gamma_{i}^{+}\Gamma_{j}^{+}\Gamma_{j}^{+}} (W q_{n_{1}} - q \zeta_{j_{i}} w_{j} w_{i_{1}}) dT
$$

=
$$
\int_{A} (\frac{\partial W}{\partial x_{i}} \overline{q} + w \frac{\partial q}{\partial x_{i}} - q_{ij} \zeta_{j_{i}} w_{i_{i1}} - q \zeta_{j_{i}} \overline{q}_{i_{i}} w_{i_{i1}} - q \zeta_{j_{i}} w_{i_{i}}) dT
$$

$$
\rightarrow \boxed{J = \int_{A} (W q_{i_{1}} - \zeta_{j_{i}} q_{i_{j}} w_{i_{i1}}) dA}
$$