Criteria for elastic fracture

When the non-linear material "process zone" near the crack tip is small compared to all other relevant length scales in the problem/structure, a K-annulus exists and lowar elastic fracture mechanics (LEFM) is applicable. This situation is referred to as small scale yielding (SST).

Then what are the conditions required for fracture? Discussions are focused on Mode I here while relevant concepts apply for other modes.

Stress intensity handbooks

Under Mode I conditions, there is an equivalence between $K_{\rm I}$ and G: $G=\frac{K_{\rm I}^2}{F'}$

One can use either G on KI to characterize the loading that leads to fracture.



There are also a number of ASTM standard tests such as compact tension (see Fracture Mechanics by A.T. Zehnder, Springer, 2012).

Initiation under monotonic, slow loading

Under ssy situations, fracture occurs when

$$G = G_c$$
 or $K_I = K_c$.
fracture toughness

The Griffith's problem is a through crack in a glass plate under tension. Assuming plane stress, G for this problem is

Griffith used glass taken from test tubos blown into thin-walled spheres and cylinders. A glass cutter was used to introduced through cracks in the test sample, which was for ther annealed to elaminate any residual stresses due to cutting.



• Temperature effect: For many materials such as metals and polymers, Kc is temperature dependent



• Thickness effect: For small thickness, there is a "loss of constraint" on the plastic zone near the crack tip.



ASTM condition for a valid Kze measurement

$$t \ge 2.5 \left(\frac{K_{TC}}{s_y}\right)^2 \simeq 16 \ \text{Fy}$$
 ensures plane strain.

$$Min(a, b, t.) \ge 2.5 \left(\frac{K_{IC}}{\delta_{Y}}\right)^2$$
 ensures $Ssy.$ $\rightarrow t > 44 \text{ mm}$

Al: KIC~ 40 MPa Im Sy ~ 300 MPa Ty ~ 2.8mm

• Slow loading: Time to load to failure is much larger than the time for a stress wave to propagate through the material specimen. K_{c} K_{c} $K_{$

K-dependency is also of importance in viscoelastic, poroelastic materials.

• Mixed mode loading: If $G = G_c$ is valid, $G = G_c$ represents an ellipsoidal "fracture surface" in K_I , K_{II} , K_{II} space. $G = \frac{K_I^2}{E'} + \frac{K_{II}^2}{E'} + \frac{K_{II}}{2M} = G_c$



Mode dependent critical fracture energy is especially important in the failure of bimaterial interfaces. Furthermore, crack loaded predominantly in Mode II tend to kink out of the crack plane. The mechanism is attributed to differences in the development of the yield/process zone in different mode (for ductile metals) or frictional effects (abscent in mode I but present in mode I & II for brittle interfaces).

The simple " criteria above let us determine whether a crack will grow or not, but they do not tell us anything about how fast, how far, or in what direction the crack will grow. These topics are to be address shorthy.

Crack growth stability (how far?)

We have shown in the analysis of the DCB speciment that $G \propto a^2$ for fixed load and $G \propto a^{-4}$ for fixed displacements. The crack growth is likely stable in the latter case since $\frac{dG}{da} < 0$. There are additional stablizing mechanisms. · Loading by compliant systems



 $P = Cq = C_{s}q_{s} , q_{t} = q + q_{s} \rightarrow q_{t} = \left(\frac{1}{C} + \frac{1}{C_{s}}\right)P$ Note that $C_{s} \rightarrow \infty \Leftrightarrow$ fixed displacement

$$\begin{aligned} \left| \int_{q_{k}}^{l} = \frac{1}{2} C q^{2} + \frac{1}{2} C_{s} q_{s}^{2} = \frac{1}{2} \frac{p^{2}}{c} + \frac{1}{2} \frac{p^{2}}{c_{s}} = \frac{1}{2} \left(\frac{1}{c} + \frac{1}{c_{s}} \right) q_{k}^{2} / \left(\frac{1}{c} + \frac{1}{c_{s}} \right)^{2} = \frac{1}{2} q_{k}^{2} / \left(\frac{1}{c} + \frac{1}{c_{s}} \right) \\ \left| q_{k} \right|^{2} = \frac{1}{2} q_{k}^{2} \frac{-\frac{1}{c^{2}} \frac{\partial c}{\partial l}}{\left(\frac{1}{c} + \frac{1}{c_{s}} \right)^{2}} = -\frac{1}{2} \frac{p^{2}}{c^{2}} \frac{\partial c}{\partial l} = -\frac{1}{2} q^{2} \frac{\partial c}{\partial l} \quad (\text{identical to the case of fixed } q) \\ \left| q_{k} \right|^{2} = \frac{1}{2} q_{k}^{2} \frac{-\frac{1}{c^{2}} \frac{\partial c}{\partial l}}{\left(\frac{1}{c} + \frac{1}{c_{s}} \right)^{2}} = -\frac{1}{2} \frac{p^{2}}{c^{2}} \frac{\partial c}{\partial l} = -\frac{1}{2} q^{2} \frac{\partial c}{\partial l} \quad (\text{identical to the case of fixed } q) \end{aligned}$$

You may find this system is also eventually stable as l increases (pt).

· Resistance curve (R-curve)

In some cases, crack growth can be stable even when $\frac{\partial G}{\partial l} > 0$. How so? For brittle materials, G_c is a constant. For ductile materials (particular thin sheets), It is generally found that G_c increases as the crack grows.



Mixed-mode fracture initiation & growth (Which direction?)



Subject to a combination of Mode-I and Mode-I loadings, crack will generally not propagate straight ahead (unless 0=0 is a weak interface).

Our previous analysis has been on $G = -\frac{\partial W}{\partial a}|_{0=0}$. What if 0=0? There are a few theories such as 0 maximum hoop stress @ maximum energy release rate. O Maximum boop stress theory: Grack will grow in the direction 0_{\star} of maximum hoop stress, when $\sqrt{\Gamma} S_{00}(\Gamma, 0_{\star}) \ge Constant$.

$$\rightarrow \frac{\partial \delta_{\theta\theta}}{\partial \theta} \bigg|_{\theta_{x}} = 0, \quad \frac{\partial^{2} \delta_{\theta\theta}}{\partial \theta^{2}} \bigg|_{\theta_{x}} < 0, \quad \delta_{\theta\theta}(r, \theta_{x}) \geqslant \frac{K_{IC}}{\sqrt{2\pi r}}$$

For this problem
$$K_I = \delta dTa \sin \beta$$
, $K_{II} = \delta dTa \cos \beta$

$$\delta_{\theta\theta}(r,\theta) = \frac{1}{\sqrt{2\pi}r} \left(K_{I} \cos \frac{\theta}{2} + \cos \theta - K_{II} \frac{3}{2} \sin \theta \cos \frac{\theta}{2} \right) + O(r^{\circ})$$



. Under pure Mode I ($\beta = 0^{\circ}$), the crack will grow at $\Theta_{*} = -70.6^{\circ}$ at a stress intensity factor of $K_{II} = 0.87$ Kic. [Allowing Kinking leads to a slightly smaller K_{II}]

② Maximum energy release rate oriterion: $\frac{\partial G}{\partial \theta_x} = 0$, $\frac{\partial^2 G}{\partial \theta_x} < 0$, $G(\theta_x) = G_c$ → $\theta_x = -75.6^\circ$ at $K_{II} = 0.817$ K_{IC} under pure Mode I loading.



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Why -70° not -45°? The presence of crack disturbs the stress field. The crack path will evolve to lie along the plane of maximum principle stress.

Mode I cyclic loading (Fatigue)

Under cyclic loading, materials can fail due to fatigue at stress levels well below their static strength.



Experimental methods

In some cases, it may not be practical to determine stress intensity factors from analytical or computational methods. For example, perhaps the loading is unknown, or is dynamic. One may wish to determine the SIF experimentally, based on local measurement of stress, strain and displacement. There are a number of experimental methods that have been developed, including photoelasticity, interferometry, digital image correlation, strain guages and so on (see Chapter 5 in Fracture Mechanics by A.T. Zehnder)

Only strain guages method by Dally and Stanford (1987) is discussed here.

$$\frac{y}{10} = \frac{1}{10} + HoTs \quad may \quad be \quad important:$$

$$\frac{y}{10} = \frac{1}{10} + \frac{1}{10} +$$

KI, Ao, A1/2 - Three parameters, but only one measure newt. What do you do?

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