The previous examples allows us to calculate or measure & directly. How can we compute & in general? - Solve the boundary value problem.

For general clasticity problems we must solve the following problem.

Kinematic: 
$$\epsilon_{ij} = \frac{1}{2} (U_{i,j} + U_{j,i})$$

First, we'll consider the in-plane bading modes:

Equilibrim : 
$$\frac{\partial G_{11}}{\partial X_1} + \frac{\partial G_{12}}{\partial X_2} = 0$$

$$\frac{\partial X^{1}}{\partial Q^{51}} + \frac{\partial X^{5}}{\partial Q^{52}} = 0$$

Kinematics:  $\epsilon_{11} = \frac{\partial U_1}{\partial x_1}$ ,  $\epsilon_{22} = \frac{\partial U_2}{\partial x_2}$ ,  $\epsilon_{12} = \epsilon_{21} = \frac{1}{2} \left( \frac{\partial U_1}{\partial x_2} + \frac{\partial U_2}{\partial x_1} \right)$ 

(4)

 $\bigcirc$ 

To solve these equations we introduce Ainy's stress function  $\phi$  such that

$$\Delta_{11} = \frac{\partial^2 \psi}{\partial x_2}, \quad \Delta_{12} = -\frac{\partial^2 \psi}{\partial x_1 \partial x_2}, \quad \Delta_{22} = \frac{\partial^2 \psi}{\partial x_1^2}.$$

Then  $S_{11,1} + S_{12,2} = \phi_{,221} - \phi_{122} = 0$ ,  $S_{12,1} + S_{22,2} = 0$ , *i.e.* equilibrium equations are automatically satisfied.  $\phi$  is not arbitrary.

$$\frac{\partial \xi_{11}}{\partial \chi_{2}^{2}} + \frac{\partial^{2} \xi_{22}}{\partial \chi_{1}^{2}} - 2 \frac{\partial^{2} \xi_{12}}{\partial \chi_{1} \partial \chi_{2}} = U_{1,1/2} + U_{2,2/1} - (U_{1,2/2} + U_{2,1/1/2}) = 0$$

Inserting Hooke's law gives

 $\delta_{11,22} - \nu' \delta_{22,22} + \delta_{22,11} - \nu' \delta_{11,11} - 2(\mu \nu') \delta_{12,12} = 0$ 

$$\phi_{,2222} - \nu' \phi_{,1122} + \phi_{,1111} - \nu' \phi_{,2211} + 2 \phi_{,1122} + 2\nu' \phi_{,1122} = 0$$

$$\rightarrow \nabla^{4} \phi = \phi_{,1111} + 2 \phi_{,1122} + \phi_{,2222} = 0$$
Bi harmonic equation

We are interested these relations in polar coordinates:

$$\begin{split} & \mathcal{S}_{1r} = \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} , \quad \mathcal{S}_{r0} = \frac{1}{r^2} \frac{\partial \phi}{\partial \theta} - \frac{1}{r} \frac{\partial^2 \phi}{\partial r^{2\theta}} , \quad \mathcal{S}_{\theta \theta} = \frac{\partial^2 \phi}{\partial r^2} \\ & \nabla^4 \phi = \nabla^2 (\nabla^2 \phi) = 0 , \quad \text{where} \quad \nabla^2 = \frac{\partial}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \end{split}$$

Known to Michell, solutions to biharmonuc equation are

$$lnr, r^2, r^2 lnr, \varphi, lnr, \varphi, r^2 \varphi, r^2 lnr, \varphi, r \varphi sin \varphi, r lnr cose, r lnr sin \varphi$$
  
 $r^s cos(s\varphi), r^s sin(s\varphi), r^{stz} cos(s\varphi), r^{s+2} sin(s\varphi)$  for any real number s

Not all of these solution are useful. For our problem, we want to invertigate the field very close to the crack tip. This requires three things:



- The solution allows discontinuity between O=±TT (Contrast to the continuity condition required in previous course)
- At  $0=\pm\pi$  for all r,  $5_{22}=5_{00}=0$  &  $5_{12}=5_{10}=0$  ( for not satisfied solutions)
- The energy in a region near the crack tip should be finite to be physical.  $U \propto \int_{\pi}^{\pi} \int_{0}^{r} \sigma^{2} r dr d\theta \propto \int_{0}^{r} \frac{\phi^{2}}{r^{4}} r dr \rightarrow finite.$

Therefore, seek solution of the form  

$$\phi = \sum_{p} r^{p+2} \left[ A_p \cos p \phi + B_p \cos (p+2)\phi + G_p \sin p \phi + D_p \sin (p+2)\phi \right]$$

$$\int \delta \Theta = \sum_{p} (p+2) (p+1) r^{p} \left[ A_{p} \cos p \Theta + B_{p} \cos (p+2)\Theta + G_{p} \sin p \Theta + D_{p} \sin (p+2)\Theta \right]$$

$$\int \delta \Theta = \sum_{p} (p+1) r^{p} \left[ pA_{p} \sin p \Theta + (p+2) B_{p} \sin (p+2)\Theta - pG_{p} \cos p \Theta - (p+2) B_{p} \cos (p+2)\Theta \right]$$

Applying the boundary conditions  $\delta \theta = \delta r \theta = 0$  at  $\theta = \pm T T$ 

$$\int A\rho \cos \rho \pi + B\rho \cos(\rho+2)\pi \pm G\rho \sin \rho \pi \pm D\rho \sin (\rho+2)\pi = D$$

$$(\pm \rho A\rho \sin \rho \pi \pm (\rho+2)B\rho \sin (\rho+2)\pi - \rho G\rho \cos \rho \pi - (\rho+2)D\rho \cos (\rho+2)\pi = 0$$

These equations can be satisfied 2 ways

• 
$$\operatorname{Sinp} \pi = 0 \implies \rho = \operatorname{integers}$$
,  $\operatorname{cosp} \pi = \pm 1$   
 $\operatorname{Ap} + \operatorname{Bp} = 0 \quad \& \quad \rho \operatorname{Cp} + (\rho + 2) \operatorname{Dp} = 0$   
•  $\operatorname{osp} \pi = 0 \implies \rho = \frac{\operatorname{odd integers}}{2}$ ,  $\operatorname{Sinp} \pi = \pm 1$   
 $\operatorname{Cp} + \operatorname{Op} = 0 \quad \& \quad \rho \operatorname{Ap} + (\rho + 2) \operatorname{Bp} = 0$ 

Let's consider the most singular term, we can write  $\delta = \Gamma^{P} \tilde{\delta}_{00/P}(0), \quad \delta_{\Gamma\Gamma} = \Gamma^{P} \tilde{\delta}_{\Gamma\Gamma/P}(0), \quad \delta_{\Gamma0} = \Gamma^{P} \tilde{\delta}_{\Gamma0/P}(0)$  $\delta_{ij} = \Gamma^{P} \tilde{\delta}_{ij/P}(0) \quad for (artesian components & b & fij = Sijke \Gamma^{P} \tilde{\delta}_{ke/P}(0)$ 

The strain energy density is

on the plane ahead of the crack (i.e., on  $\theta=0$ ). Soo  $|_{\theta=0} = \delta_{y} |_{x=0} \frac{A}{F'^{1_2}} \rightarrow A = \sqrt{x_T}$  $\delta_{xy}|_{x=0} = \delta_{r0}|_{\theta=0} = \frac{C}{F'^2} \rightarrow C = \frac{K_T}{\sqrt{x_T}}$ 

$$\Rightarrow \delta_{\theta\theta} = \frac{K_{I}}{\sqrt{2\pi r}} \underbrace{\left(\frac{3}{4} \cos \frac{9}{2} + \frac{1}{4} \cos \frac{30}{2}\right)}_{S_{\theta\theta}} + \frac{K_{II}}{\sqrt{2\pi r}} \underbrace{\left(-\frac{3}{4} \sin \frac{9}{2} - \frac{3}{4} \sin \frac{30}{2}\right)}_{S_{\theta\theta}} \\ \delta_{r\theta} = \frac{K_{I}}{\sqrt{2\pi r}} \underbrace{\left(\frac{1}{4} \sin \frac{9}{2} + \frac{1}{4} \sin \frac{30}{2}\right)}_{S_{r\theta}} + \frac{K_{II}}{\sqrt{2\pi r}} \underbrace{\left(\frac{1}{4} \cos \frac{9}{2} + \frac{3}{4} \cos \frac{30}{2}\right)}_{S_{r\theta}} \\ \delta_{rr} = \frac{K_{I}}{\sqrt{2\pi r}} \underbrace{\left(\frac{5}{4} \cos \frac{9}{2} - \frac{1}{4} \cos \frac{30}{2}\right)}_{S_{r\theta}} + \frac{K_{II}}{\sqrt{2\pi r}} \underbrace{\left(-\frac{5}{4} \sin \frac{9}{2} + \frac{3}{4} \sin \frac{30}{2}\right)}_{S_{r\theta}} \\ \delta_{rr} = \frac{K_{I}}{\sqrt{2\pi r}} \underbrace{\left(\frac{5}{4} \cos \frac{9}{2} - \frac{1}{4} \cos \frac{30}{2}\right)}_{S_{rr}} + \frac{K_{II}}{\sqrt{2\pi r}} \underbrace{\left(-\frac{5}{4} \sin \frac{9}{2} + \frac{3}{4} \sin \frac{30}{2}\right)}_{S_{rr}} \\ \underbrace{\left(-\frac{5}{4} \sin \frac{9}{2} + \frac{3}{4} \sin \frac{9}{2}\right)}_{S_{rr}} \\ \underbrace{\left(-\frac{5}{4} \sin$$

The Cartesian components can be written as

$$\begin{split} \delta_{XX} &= \frac{K_{T}}{\sqrt{2\pi r}} \left[ \cos \frac{\Theta}{2} \left( 1 - \sin \frac{\Theta}{2} \sin \frac{3\Theta}{2} \right) \right] + \frac{K_{T}}{\sqrt{2\pi r}} \left[ -\sin \frac{\Theta}{2} \left( 2 + \cos \frac{\Theta}{2} \cos \frac{3\Theta}{2} \right) \right] \\ \delta_{YY} &= \frac{K_{T}}{\sqrt{2\pi r}} \left[ \cos \frac{\Theta}{2} \left( 1 + \sin \frac{\Theta}{2} \sin \frac{3\Theta}{2} \right) \right] + \frac{K_{T}}{\sqrt{2\pi r}} \sin \frac{\Theta}{2} \cos \frac{\Theta}{2} \cos \frac{3\Theta}{2} \right] \\ \delta_{XY} &= \frac{K_{T}}{\sqrt{2\pi r}} \sin \frac{\Theta}{2} \cos \frac{\Theta}{2} \cos \frac{3\Theta}{2} + \frac{K_{T}}{\sqrt{2\pi r}} \left[ \cos \frac{\Theta}{2} \left( 1 - \sin \frac{\Theta}{2} \sin \frac{3\Theta}{2} \right) \right] \end{split}$$

KI and KI have dimensions of  $SL^{V_2}$  and are called the mode I and mode I stress intensity factors. In general, these constants need to be determined based on the specific loading and geometry of the specimen.



0

Mode I stress field angular dependence



Mode Il stress field angular dependence



The corresponding displacement fields are

$$\int \mathcal{U}_{r} = \frac{K_{\mathrm{T}}}{2E} \sqrt{\frac{\Gamma}{2\pi}} (1+\nu) \left[ (2\mathcal{K}-1) \cos \frac{\theta}{2} - \cos \frac{3\theta}{2} \right] + \frac{K_{\mathrm{T}}}{2E} \sqrt{\frac{\Gamma}{2\pi}} (1+\nu) \left[ -(2\mathcal{K}-1) \sin \frac{\theta}{2} + 3\sin \frac{3\theta}{2} \right]$$
$$\mathcal{U}_{0} = \frac{K_{\mathrm{T}}}{2E} \sqrt{\frac{\Gamma}{2\pi}} (1+\nu) \left[ -(2\mathcal{K}+1) \sin \frac{\theta}{2} + \sin \frac{3\theta}{2} \right] + \frac{K_{\mathrm{T}}}{2E} \sqrt{\frac{\Gamma}{2\pi}} (1+\nu) \left[ -(2\mathcal{K}+1) \cos \frac{\theta}{2} + 3\cos \frac{3\theta}{2} \right]$$

$$\begin{cases} \mathcal{U}_{x} = \frac{K_{\mathrm{I}}}{2\mathrm{E}} \int_{2\pi}^{\Gamma} (H\nu) \left[ (2\mathrm{K}-1) \cos \frac{\theta}{2} - \cos \frac{3\theta}{2} \right] + \frac{K_{\mathrm{I}}}{2\mathrm{E}} \int_{2\pi}^{\Gamma} (H\nu) \left[ (2\mathrm{K}+3) \sin \frac{\theta}{2} + \sin \frac{3\theta}{2} \right] \\ \mathcal{U}_{y} = \frac{K_{\mathrm{I}}}{2\mathrm{E}} \int_{2\pi}^{\Gamma} (H\nu) \left[ (2\mathrm{K}+1) \sin \frac{\theta}{2} - \sin \frac{3\theta}{2} \right] + \frac{K_{\mathrm{I}}}{2\mathrm{E}} \int_{2\pi}^{\Gamma} (H\nu) \left[ -(2\mathrm{K}-3) \cos \frac{\theta}{2} - \cos \frac{3\theta}{2} \right] \end{cases}$$

where  $K = \begin{cases} 3-4\nu \\ \frac{3-\nu}{1+\nu} \end{cases}$  plane stress.

Now, consider the p=0 term.

$$\phi = (A_0 + B_0 \cos 2\theta + D_0 \sin 2\theta) r^2$$

Boundary conditions give Ao=-Bo, Do=0

$$\phi = A_{0} \left( 1 - \cos 2\theta \right) \Gamma^{2}$$

$$\delta_{\theta\theta} = \frac{\partial^{2} \phi}{\partial r^{2}} = 2A_{0} (1 - \cos 2\theta)$$

$$\delta_{rr} = \frac{1}{r} \frac{\partial \phi}{\partial r} + \frac{1}{r^{2} \partial \theta^{2}} = 2A_{0} (1 - \cos 2\theta) + 4A_{0} \cos 2\theta = 2A_{0} (1 + \cos 2\theta)$$

$$\delta_{r\theta} = \frac{1}{r^{2}} \frac{\partial \phi}{\partial \theta} - \frac{1}{r} \frac{\partial^{2} \phi}{\partial r \partial \theta} = 2A_{0} \sin 2\theta - 4A_{0} \sin 2\theta = -2A_{0} \sin 2\theta$$

(21)

Let 2A0 = Txx by convention, which is called the "T stress". Transforming to Cartislan coordinates gives T stress terms (O(1)):

$$d_{xx}=T_{xx}$$
,  $d_{yy}=0$ ,  $d_{xy}=0$ 

Also note that a uniaxial stress in the  $X_3$  direction can be applied and BCs Will still be satisfied, so there is a  $T_{33}$  ( $T_{22}$ ) T-stress term on the order of r<sup>o</sup> as well:

Finally, there exists another mode of crack loading called mode II. This mode is a "tearing" mode and results from anti-plane/longitudinal shear.



To solve the fields very close to the Mode II crack tip, consider the following equations for longitudinal shear in isotropic elasticity

Equilibrium: 
$$\frac{\partial G_{13}}{\partial x_{1}} + \frac{\partial G_{23}}{\partial x_{2}} = 0$$
  
Kinemetrics:  $G_{13} = \frac{1}{2} \frac{\partial U_{3}}{\partial x_{1}}$ ,  $G_{23} = \frac{1}{2} \frac{\partial U_{3}}{\partial x_{2}}$   
Hooke's law:  $G_{13} = 2\mu \in I_{3}$ ,  $G_{23} = 2\mu \in I_{23}$ ,  $\mu = \frac{E}{2(H\nu)}$ 

In HW2, you will be in change of finding the asymptotic KIT field and any T-stresses.

Therefore, stress field near a crack tip can be enpanded in the following way

$$\begin{split} d_{ij} &= \frac{K_{I}}{\sqrt{2\pi r}} \, \widetilde{\mathcal{G}}_{ij}^{I}(0) \, + \, \frac{K_{II}}{\sqrt{2\pi r}} \, \widetilde{\mathcal{G}}_{ij}^{II}(0) \, + \, \frac{K_{II}}{\sqrt{2\pi r}} \, \widetilde{\mathcal{G}}_{ij}^{II}(0) \, & \qquad \textit{Loading order} \\ &+ T_{II} \, \delta_{i1} \, \delta_{j1} \, + \, T_{33} \, \delta_{i3} \, \delta_{j3} \, + \, T_{I3} \left( \delta_{i1} \, \delta_{j3} \, + \, \delta_{i3} \, \delta_{j1} \right) \\ &+ \, \mathcal{O}(r^{1/2}) \, + \, \mathcal{O}(r) \, + \, \mathcal{O}(r^{3h}) \, + \, \cdots \end{split}$$

This gives rise to the idea of "K-annulus", in which the leading order K terms are valid.



•Within the region inside Rm, the assumptions of linear elasticity break down, i.e., physically stresses do not → 00. This is usually manifested in some type of non-linear material bevaviors such as yielding for <u>ductile materials</u> and "peak" stresses observed in the first leture for "perfectly brittle" materials



• In the region outside  $R_G$ , higher-order terms (T stresses and above) arising due to the introduction of a length scale from the specimen geometry become important. (We are able to tell what is meant by r=1).

Energy release rate is all we asked for from the BVP. Now we have known  $K_{\rm I}$ ,  $K_{\rm II}$ ,  $K_{\rm III}$  as "integration constants" to be determined. Beforce getting to this part, let's determine the relationship between  $G \sim \frac{\rm Energy}{L^2}$  and  $K \sim {\rm strens} L^{\rm h}$  while we expect  $G \sim K^{\circ}/E$ 

Irwin performed the following "crack closure" integral to determine how much energy is "needed" to "close" the crack tip by an increment of Sa for Mode I. "released" "open"



As we apply such traction, the crack opening displacement (COD) goes from

$$(OD = U_{y}(r', \pi) - U_{y}(r', -\pi) = \frac{K_{I}}{E} \sqrt{\frac{r}{2\pi}} (1+\nu)(2K+2)$$

to zero. For any point along the closing region, we should have a linear tradim - separation relation

$$\int \frac{1}{2} \delta y_{1}(r) \cdot CDD(r^{1})$$
Energy (per area) to close the point at r, or  
at r'= 5a-r  

$$\int W = \int_{0}^{\delta a} \frac{1}{2} \delta y_{1}(r) \cdot COD(\delta a-r) dr \times t^{k-1} thickness$$

$$= \frac{1}{2} \frac{k_{T}}{\sqrt{2\pi}} \cdot \frac{k_{T}}{E} \cdot \frac{(H\nu)(2k+2)}{\sqrt{2\pi}} \int_{0}^{\delta a} \sqrt{\frac{5a-r}{r}} dr$$

$$= \frac{k_{T}^{2} t}{E} \frac{(H\nu)(k+1)}{2\pi} \int_{0}^{\frac{\pi}{2}} 2\delta a \cdot \frac{COS\theta}{SNO} SNO COSP d\theta$$

$$= \frac{k_{T}^{2} t}{2\delta a} \frac{(H\nu)(k+1)}{\sqrt{2\pi}} \int_{0}^{\frac{\pi}{2}} 2\delta a \cdot \frac{COS\theta}{SNO} SNO COSP d\theta$$

$$= \frac{k_{T}^{2} t}{2\delta a} \frac{(H\nu)(k+1)}{2\pi} \int_{0}^{\frac{\pi}{2}} 2\delta a \cdot \frac{COS\theta}{SNO} SNO COSP d\theta$$

$$= \frac{K_{I}^{2} t \delta a}{E} \frac{(H\nu)(K+I)}{4} = \int \delta a \times t$$

$$\rightarrow \int G = \frac{K_{I}^{2}}{E^{1}} = \begin{cases} \frac{K_{I}^{2}}{E} & \text{plane stress} \\ \frac{K_{T}^{2}(H\nu)}{E} & \text{plane strain} \end{cases}$$

We will find similar vesults for Mode II and Mode II and obtain

$$G = \frac{K_{I}^{2}}{E'} + \frac{K_{II}}{E'} + \frac{K_{II}}{2M}$$
Will proof this in HW4
with J- integral method

for isotropic linear elastic solids (modes are decoupled). Note that streppes and displacements are linear in K but non-linear in B. Therefore K values can be added for two superposed elasticity problems (solutions but B cannot be added in general.

$$K_{I} = K_{I}^{(1)} + K_{I}^{(2)}, \quad G^{(1)} = \frac{\left(K_{I}^{(1)}\right)^{2}}{E'}, \quad G^{(2)} = \frac{\left(K_{I}^{(2)}\right)^{2}}{E'}, \quad G = \frac{K_{I}^{2}}{E'} \neq G^{(1)} + G^{(2)}$$

One exception is the decoupling of Mode I, I, & II in isotropic elasticity. For anisotropic elasticity

$$G = \sum_{i=1}^{m} \sum_{j=1}^{m} K_i H_{ij} K_j$$

where 
$$H = \begin{bmatrix} \frac{1}{E} & 0 & 0 \\ 0 & \frac{1}{E} & 0 \\ 0 & 0 & \frac{1}{E} \\ 0 & 0 & \frac{1}{E} \\ \end{bmatrix}$$
 for isotropic elegiticity.